

PCC Vivace: Online-Learning Congestion Control

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Internet Congestion Control

[Winstein et al.]

- Offline-opt
- Generated



pla
FAST
H-TCP

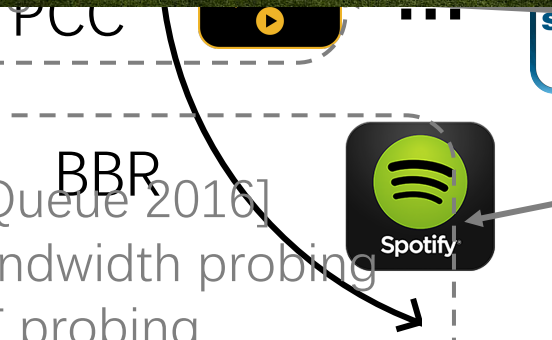
[Dong et al.]

- Utility fram
- Online lea

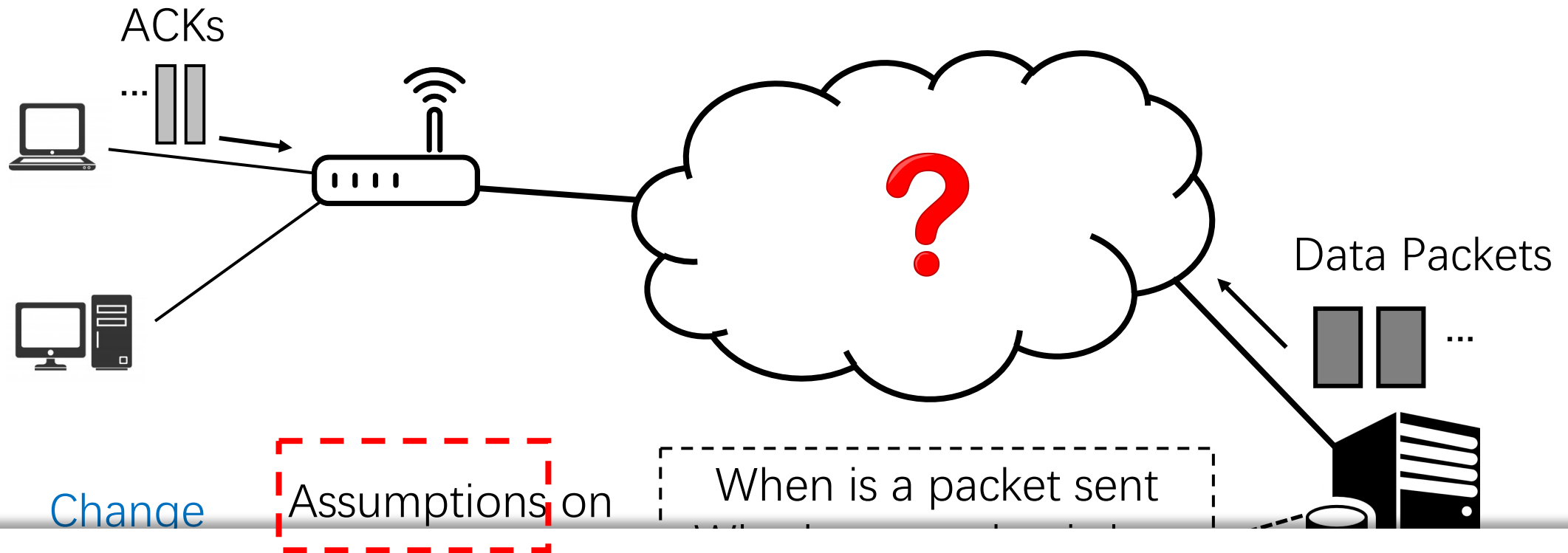


[Cardwell et al. Queue 2016]

- Bottleneck bandwidth probing
- Minimum RTT probing

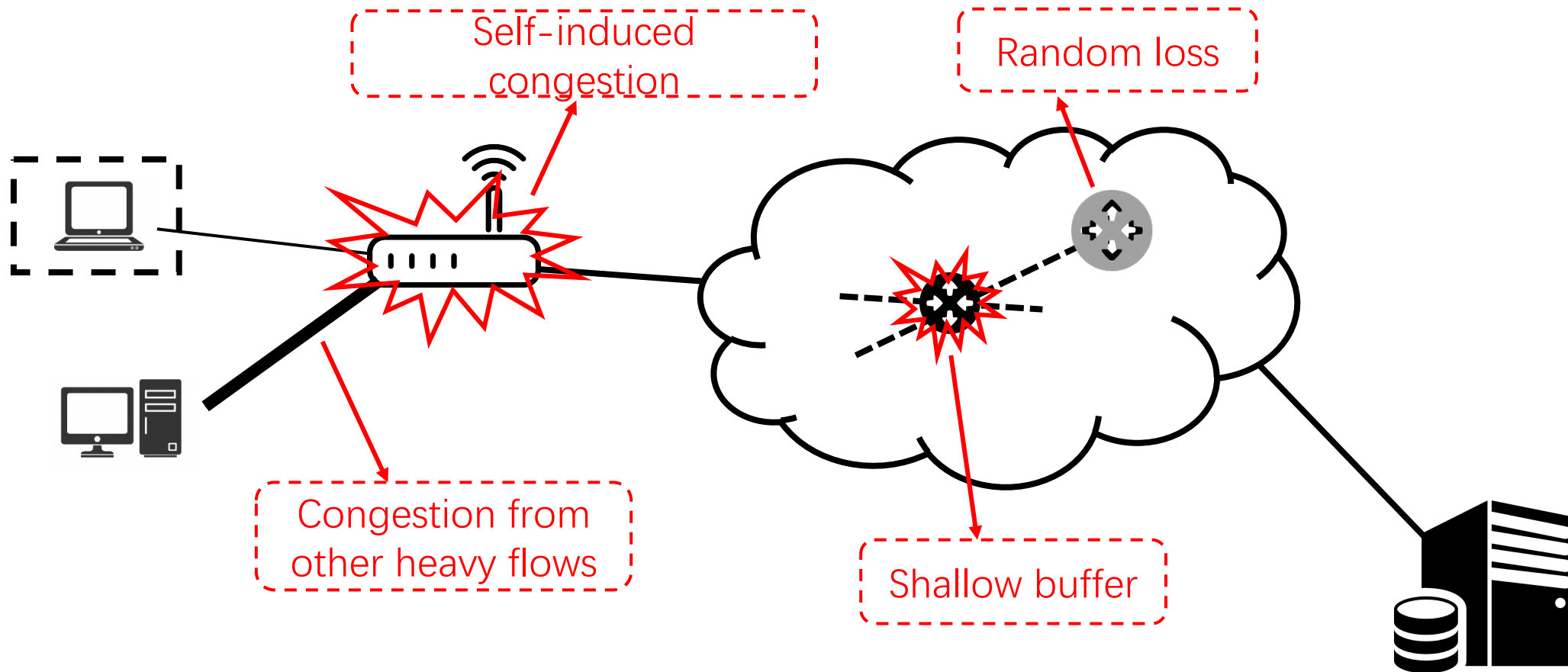


Internet Congestion Control

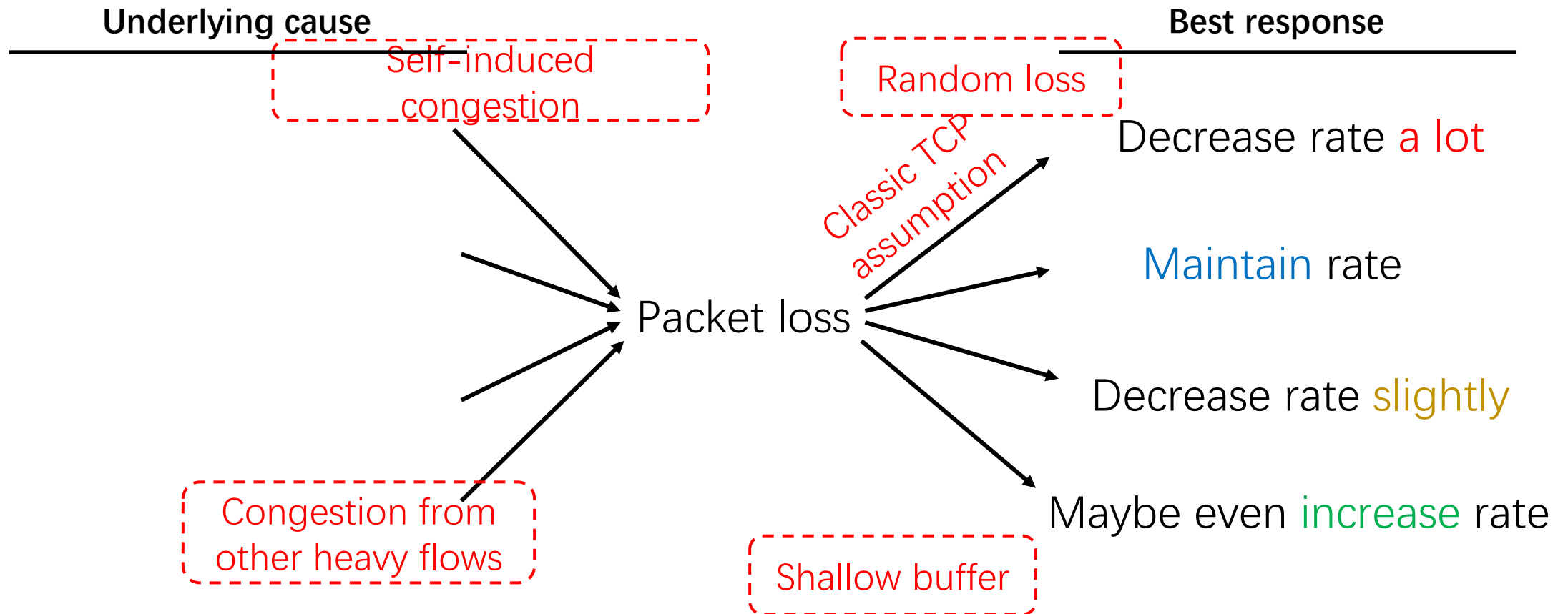


Packet loss / RTT increment indicates congestion

Internet Congestion Control

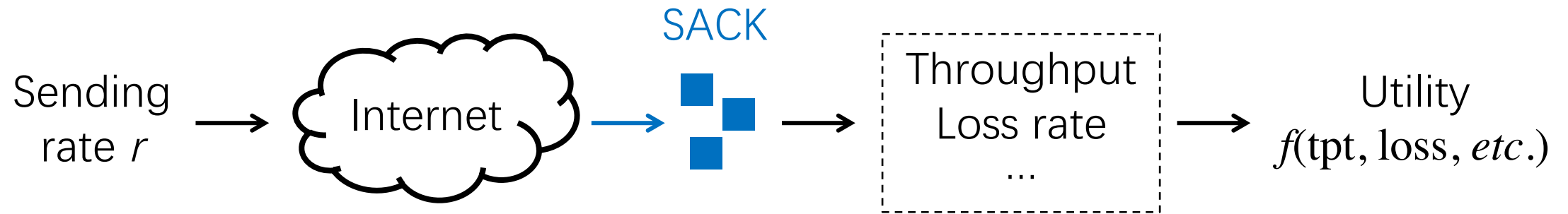


Strong Assumptions Cause Problem

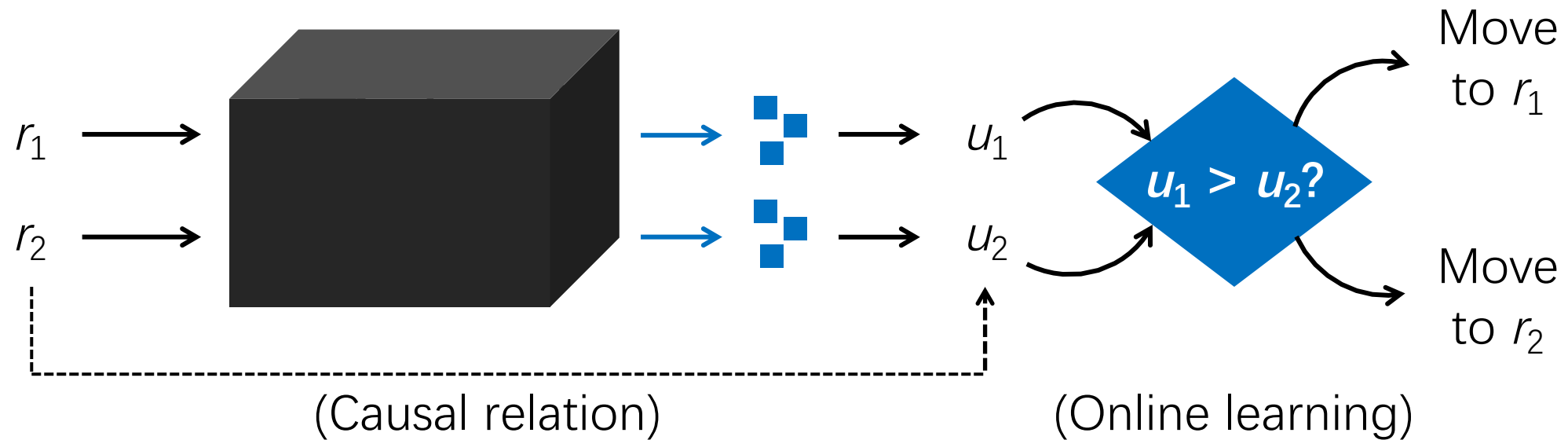


Abstract assumption cannot capture Internet complexity

PCC Utility Framework

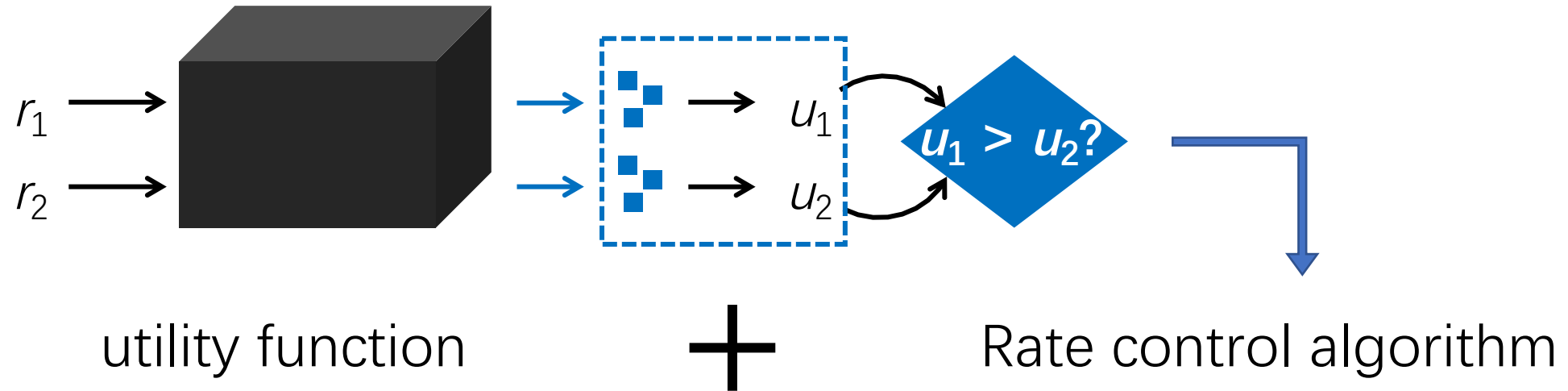


PCC Rate Control



Sender selfishly maximizes its own utility
(*online learning in non-cooperative game*)

PCC Design Challenges



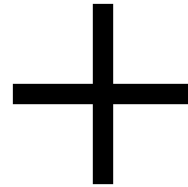
Requirements for consistently high performance:

- Capture application performance objectives
- Guarantee equilibrium with multiple competing senders
- Guarantee reaching equilibrium upon convergence
- Rapidly adapt to network dynamics

PCC Allegro

[Dong et al. NSDI 2015]

Loss-based
utility function



Heuristic
rate control

$$u_i(x_i) = T_i \cdot \text{Sigmoid}_\alpha(L_i - 0.05) - x_i \cdot L_i$$

$$T_i = x_i(1 - L_i)$$

$$\text{Sigmoid}_\alpha(y) = \frac{1}{1 + e^{\alpha y}}$$



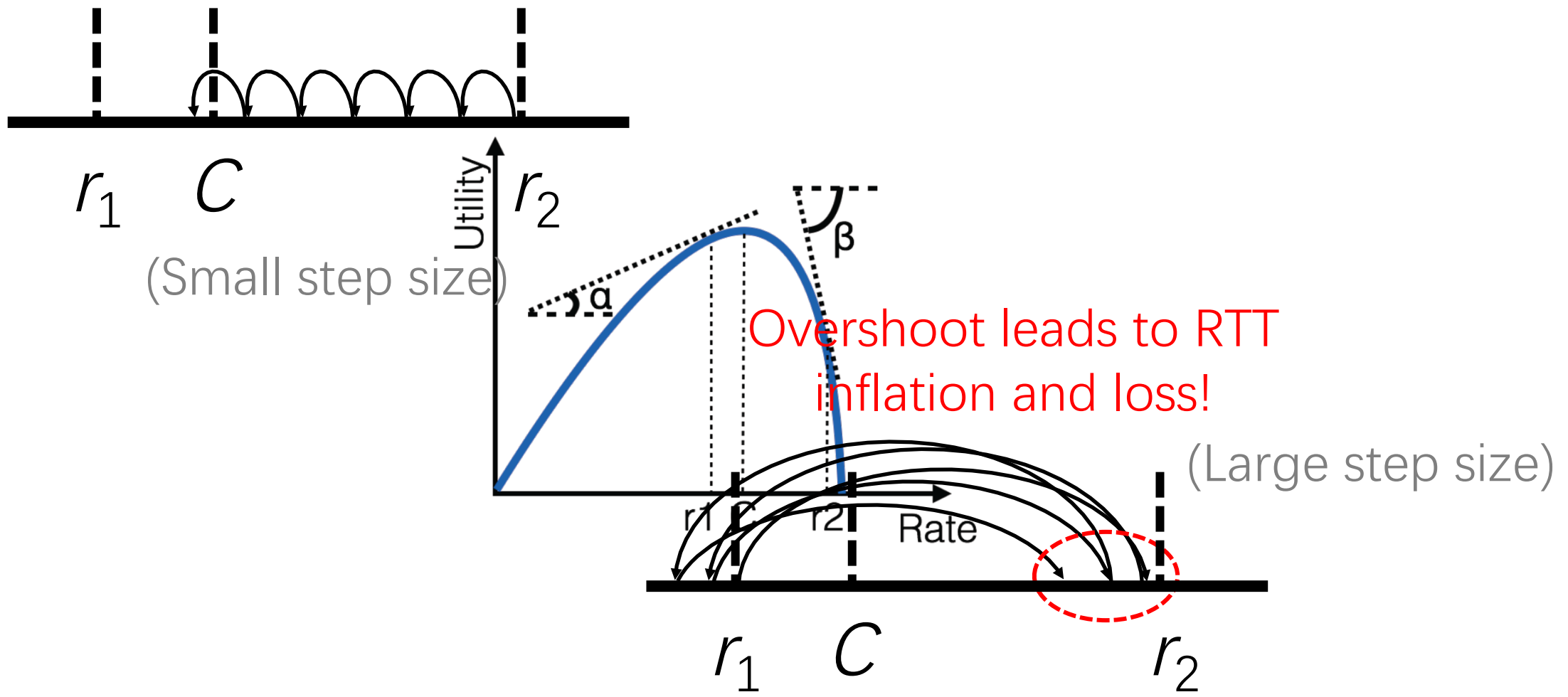
No latency-awareness
Can cause bufferbloat

*Fixed rate
change step size*



Slow convergence
Slow reaction to network changes

RTT / loss keeps increasing!



PCC Vivace

- Leveraging powerful tools from online learning theory

New utility function framework

- Latency-awareness
- Strictly concave \Rightarrow Equilibrium guarantee
- Flexibility among senders

New control algorithm

- Gradient-ascent \Rightarrow Convergence speed/stability
- Deals with measurement noise

PCC Vivace

Strictly concave
utility function

Strict socially concave game
Unique convergence equilibrium

$$u \left(x_i, \frac{d(RTT_i)}{dT}, L_i \right) = x_i^t - \boxed{bx_i} \frac{d(RTT_i)}{dT} - \boxed{cx_i} \times L_i$$

$$0 < t < 1, b \geq 0, c > 0$$

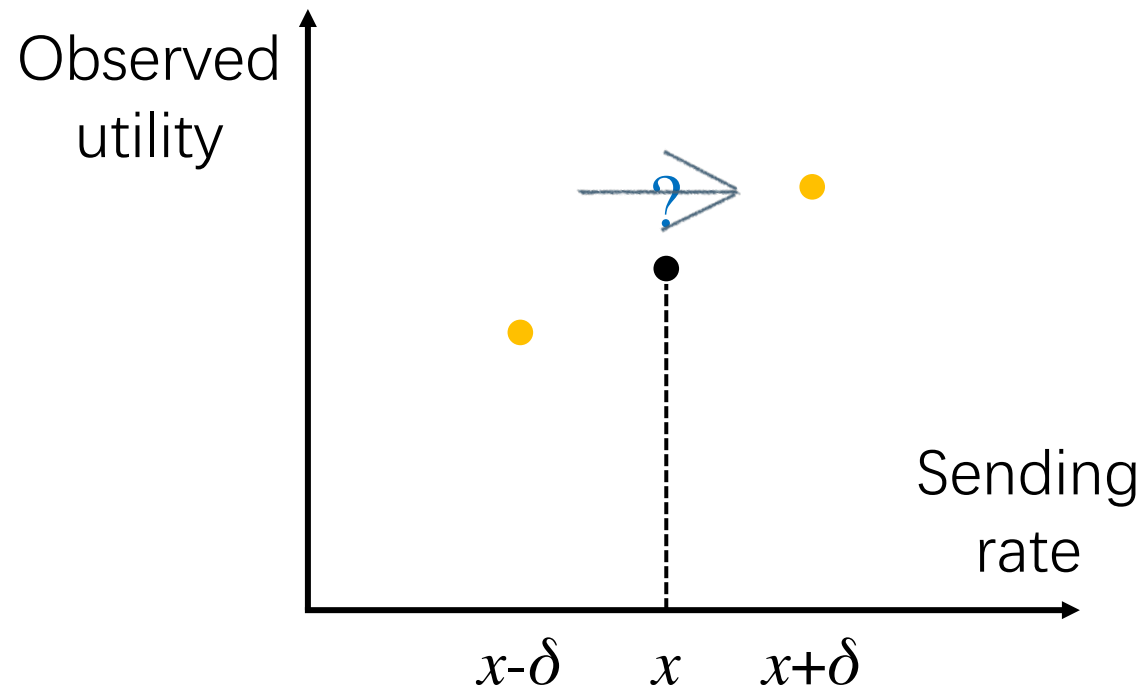
Tolerate p-random-loss if

$$c = \frac{tC^{t-1}}{p}$$

No latency inflation
upon convergence if

$$b \geq tn^{2-t}C^{t-1}$$

PCC Vivace

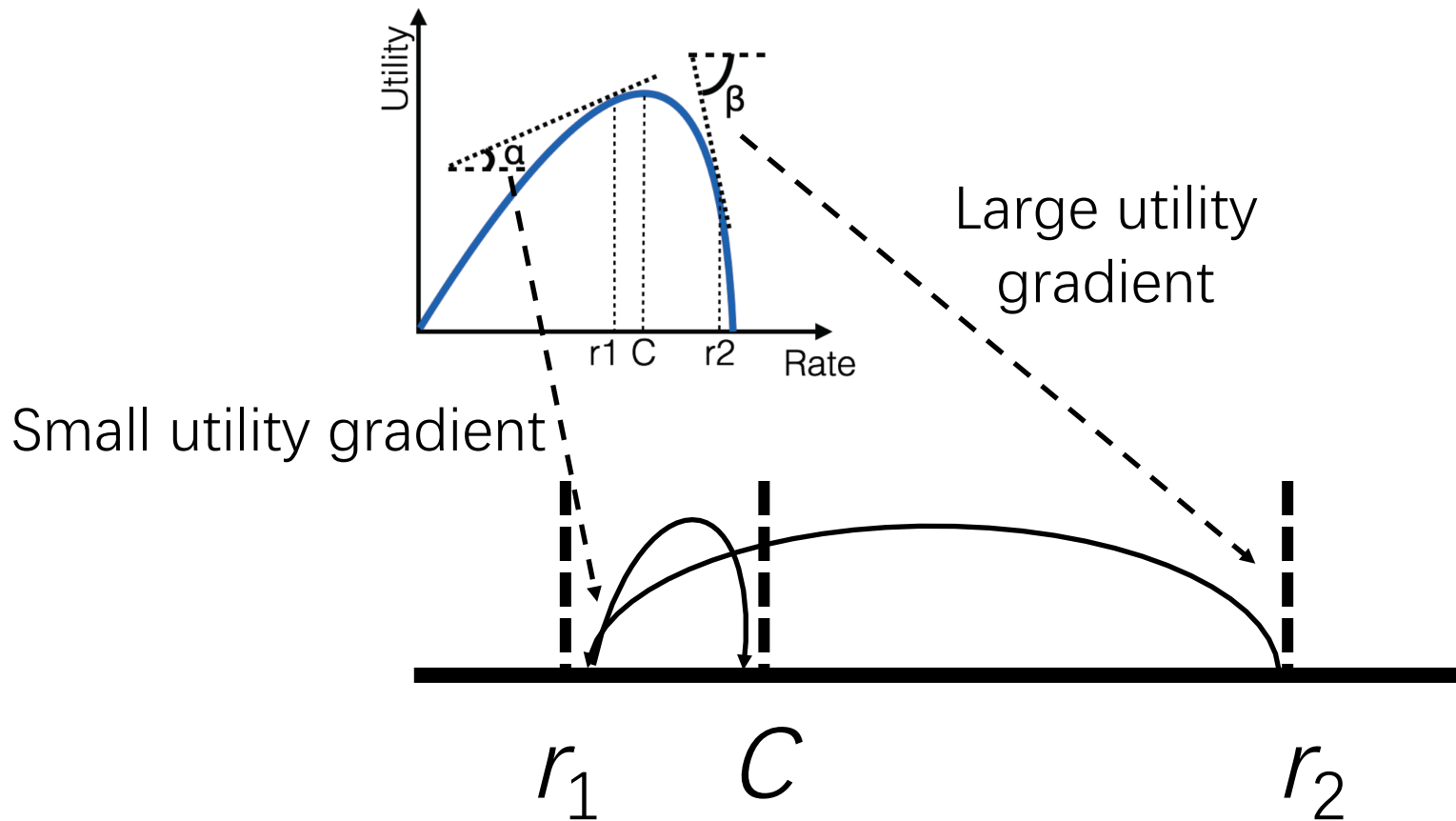


Gradient-ascent
rate control

$$\frac{u(x + \delta) - u(x - \delta)}{2\delta} \rightarrow \alpha \cdot \Delta x$$

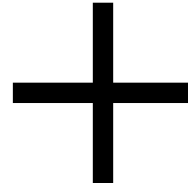
Techniques to deal with
measurement noise:

- Linear regression
- RTT gradient low-pass filter
- Double check



PCC Vivace

Strictly concave
utility function



Gradient-ascent
rate control

$$u\left(x_i, \frac{d(RTT_i)}{dT}, L_i\right) = x_i^t - bx_i \frac{d(RTT_i)}{dT} - cx_i \times L_i$$

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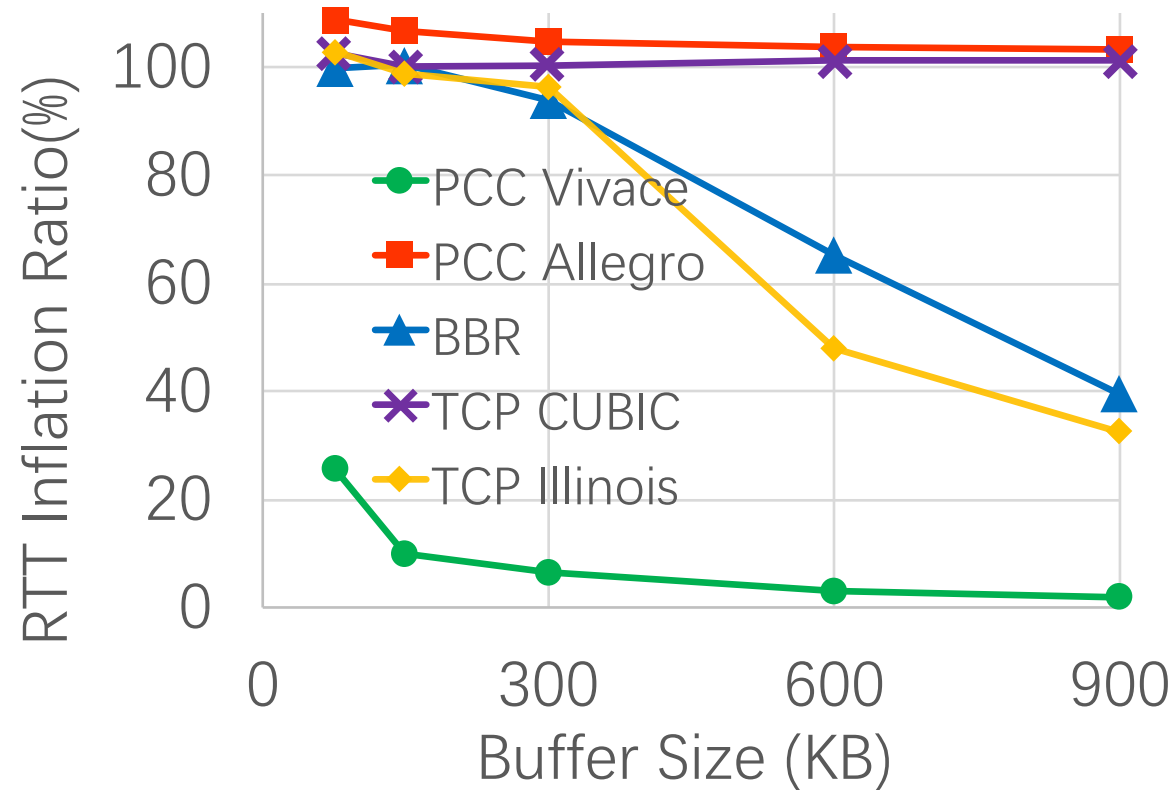
"No-regret" guarantee:
A Powerful lens for analysis

Evaluation

- Implementation
 - UDT-based user-space implementation
 - Emulab experiments, Amazon EC2 experiments
 - User-space PCC proxy for video streaming
- Protocols for comparison
 - TCP variants (TCP CUBIC, TCP Illinois, TCP Vegas, *etc.*)
 - BBR
 - PCC Allegro
 - PCC Vivace

Vivace Utility Performance

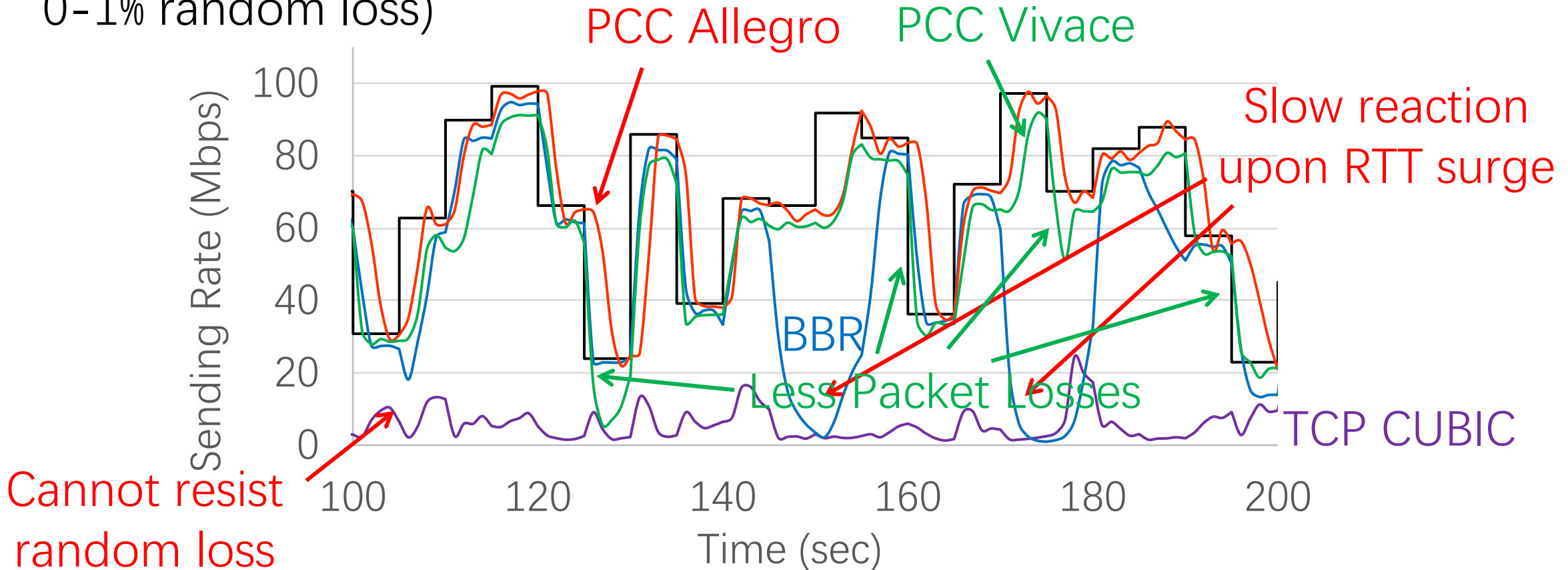
- Latency awareness (100Mbps, 30ms RTT Emulab bottleneck link)



< 2ms inflation in all cases
90% smaller than BBR under 2BDP

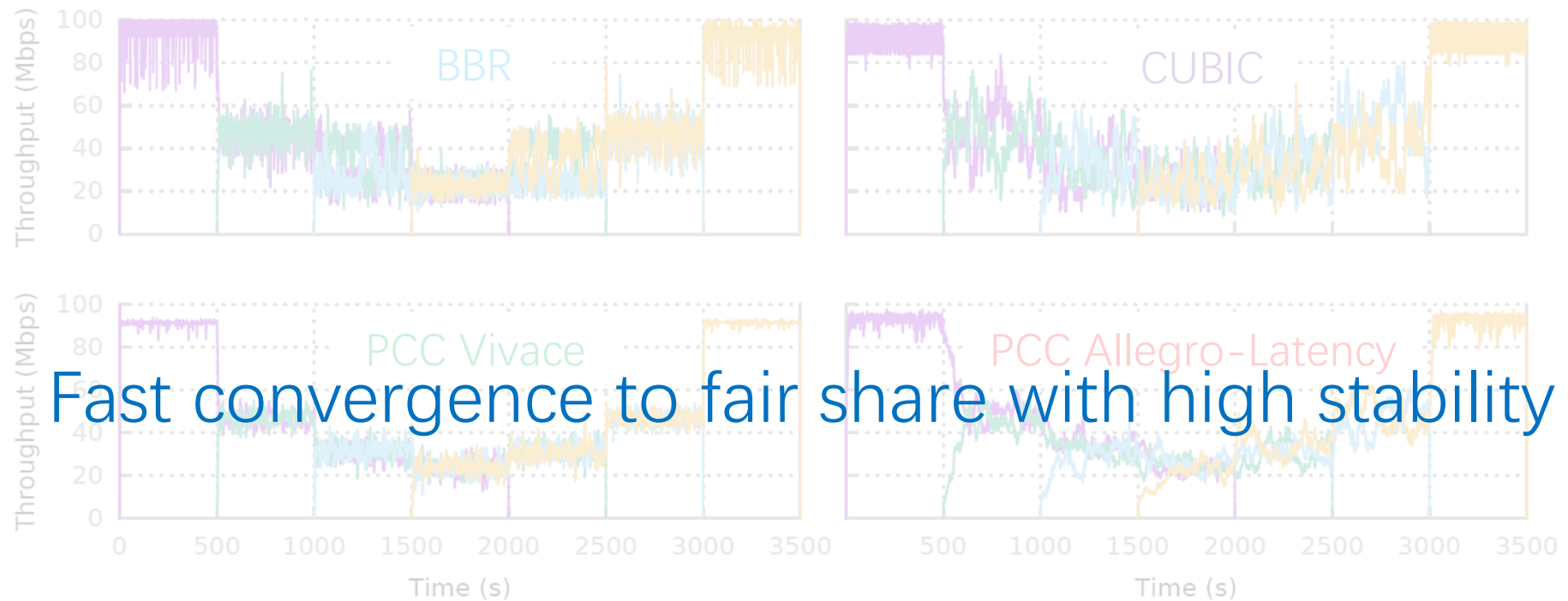
Vivace Rate Control Performance

- Rapid reaction to network changes (10-100Mbps, 10-100ms RTT, 0-1% random loss)



Vivace upon Convergence

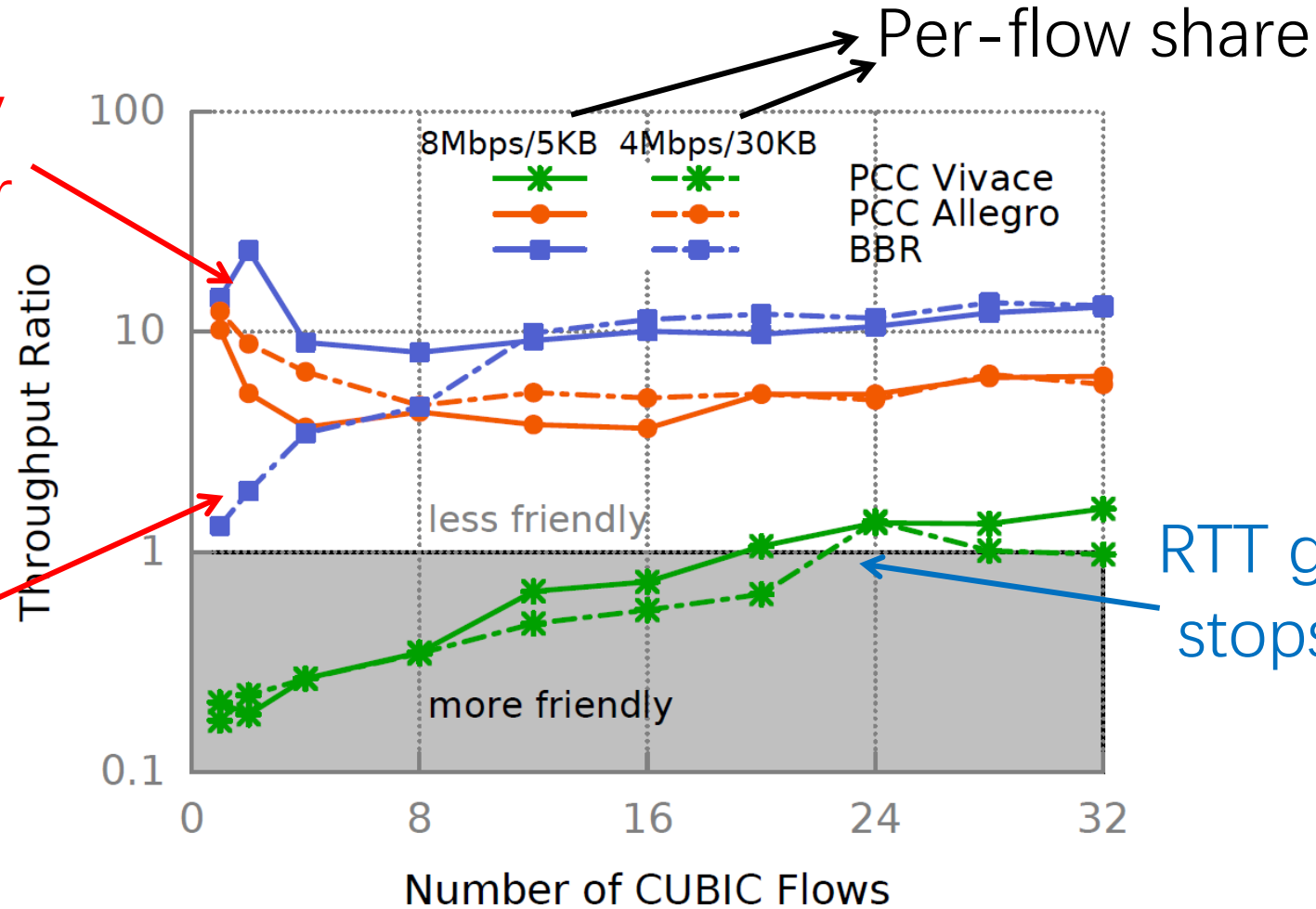
- Fair equilibrium (100Mbps, 30ms RTT, 75KB buffer)



TCP Friendliness

BBR not friendly with small buffer

BBR keeps grabbing 50% bandwidth

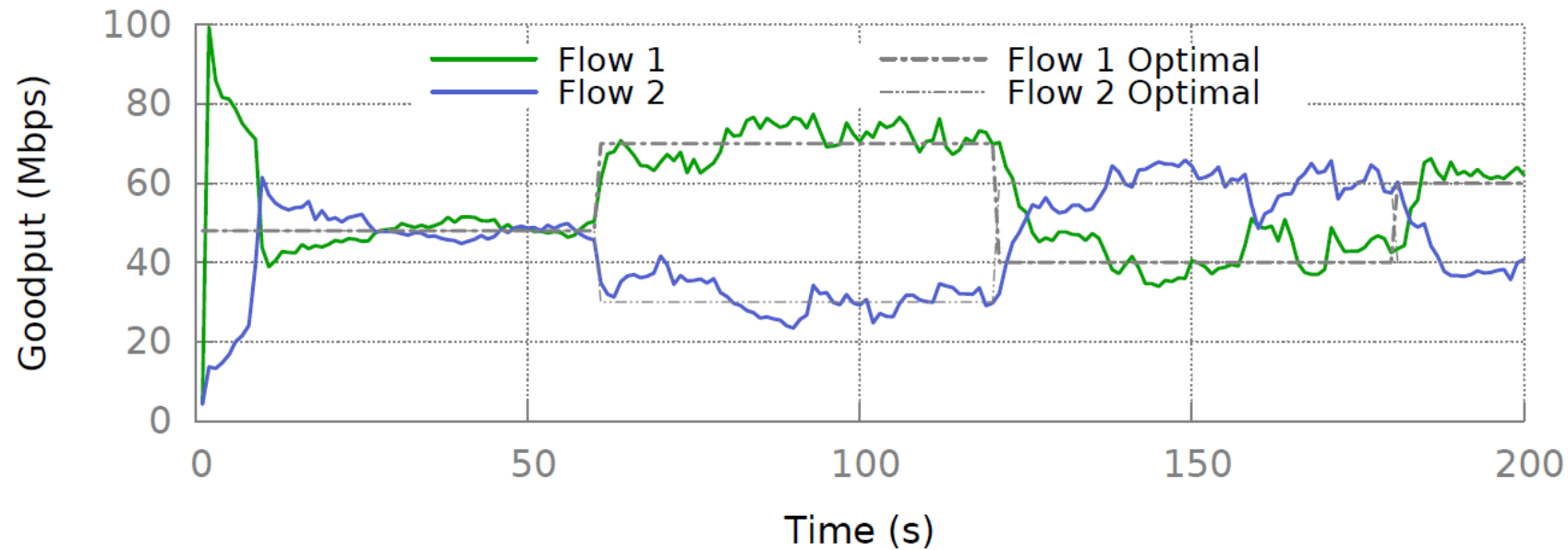


RTT gradient $\rightarrow 0$, stops being over friendly

Insights from Learning-Theoretic Tools

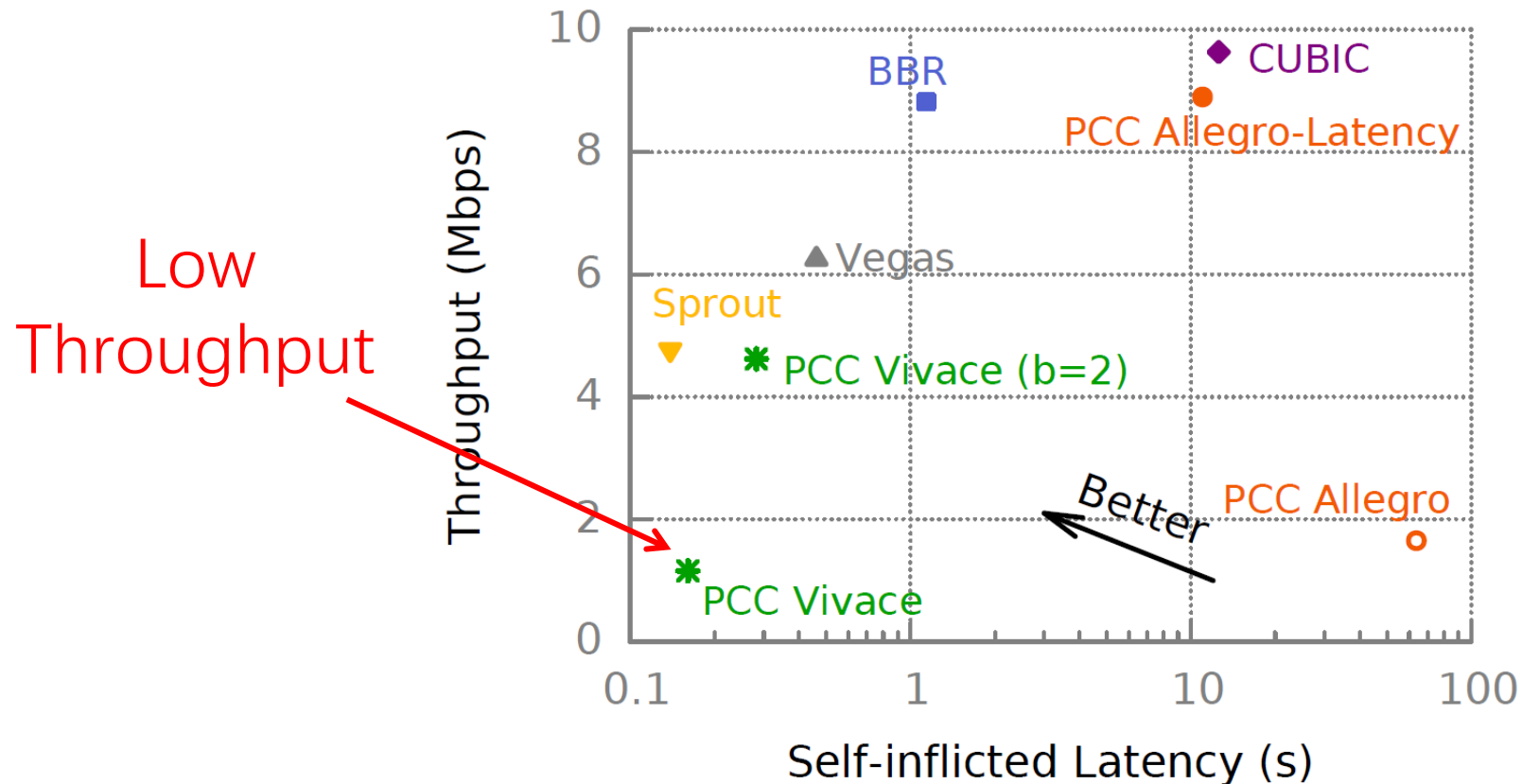
- Flexible equilibrium state with heterogeneous senders

$$u(x_i, L_i) = x_i - c_i x_i \left(\frac{1}{1 - L_i} - 1 \right) \quad c_i = \frac{C}{x_i^*}$$



Limitation in Extremely Dynamic Networks

- LTE (Mahimahi emulator [Netravali et al. ATC 2015])



<https://www.youtube.com/watch?v=Y3IzuCdwdUo&t=27s>
(Demo comparing PCC with UDP and TCP video streaming)

PCC In Action

- Open source release on GitHub (<https://github.com/pccproject>)
 - UDP implementation used in experiments presented here
 - QUIC implementation with 
 - Pantheon implementation for test purpose
 - Kernel implementation in the works
- VACC variant of PCC by  **HUAWEI** and  **vodafone**
 - Kernel implementation with optimizations for video over LTE
 - Ongoing research project with successful field tests

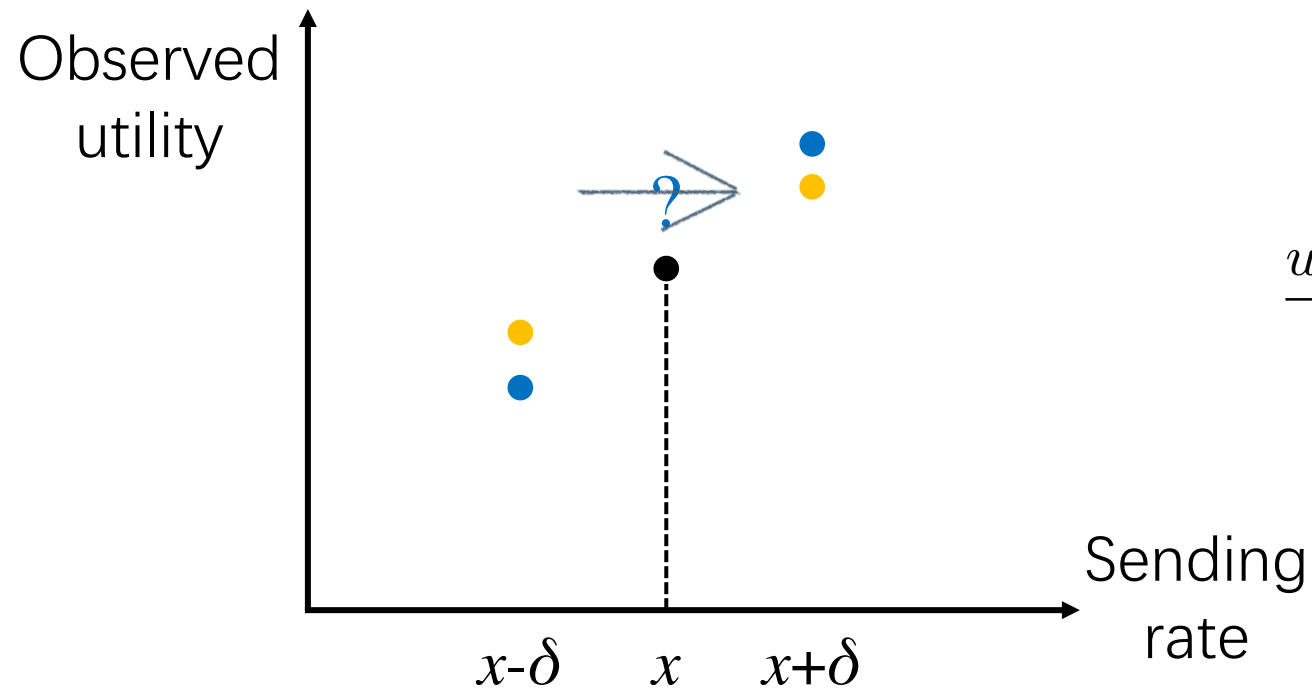
Conclusion

- PCC Vivace: Leveraging no-regret learning for congestion control
 - Consistent high performance as PCC Allegro
 - Latency awareness, mitigated bufferbloat (latency inflation, congestion loss)
 - Provably fair, yet also flexible equilibrium convergence
 - Fast and stable convergence, even with changing network conditions
 - Improved TCP friendliness, safer to deploy
- Thanks for generous project support



Thanks!

PCC Vivace



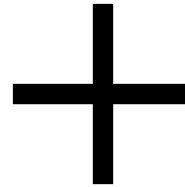
~~Gradient-ascent~~
Heuristic
rate control

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PCC Vivace

Strictly concave

~~Loss based~~
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Gradient-ascent

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$$0 < t < 1, b \geq 0, c > 0$$

Linear regression
Low pass filter (> 0.01)

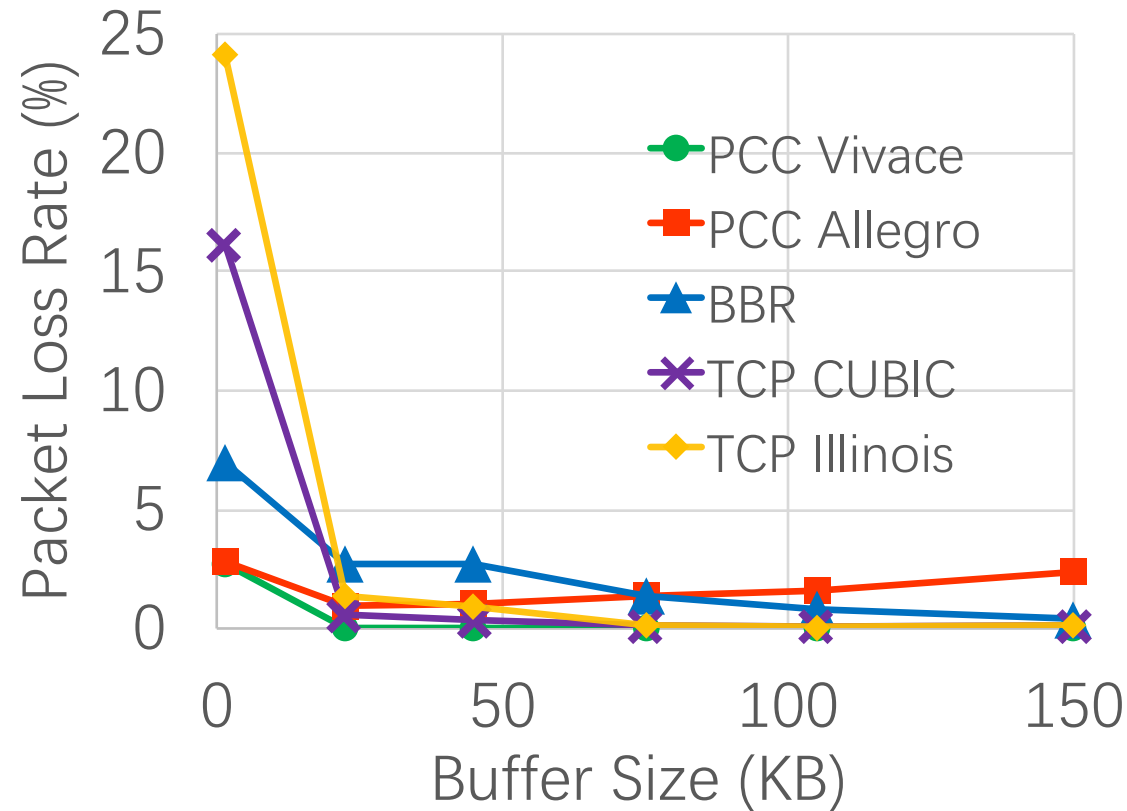
$$\frac{u(x + \delta) - u(x - \delta)}{2\delta} \rightarrow \alpha \cdot \Delta x$$

$$L(x + \delta) = 0.01\% \quad L(x - \delta) = 2.0\%$$

Double check

Vivace Utility Performance

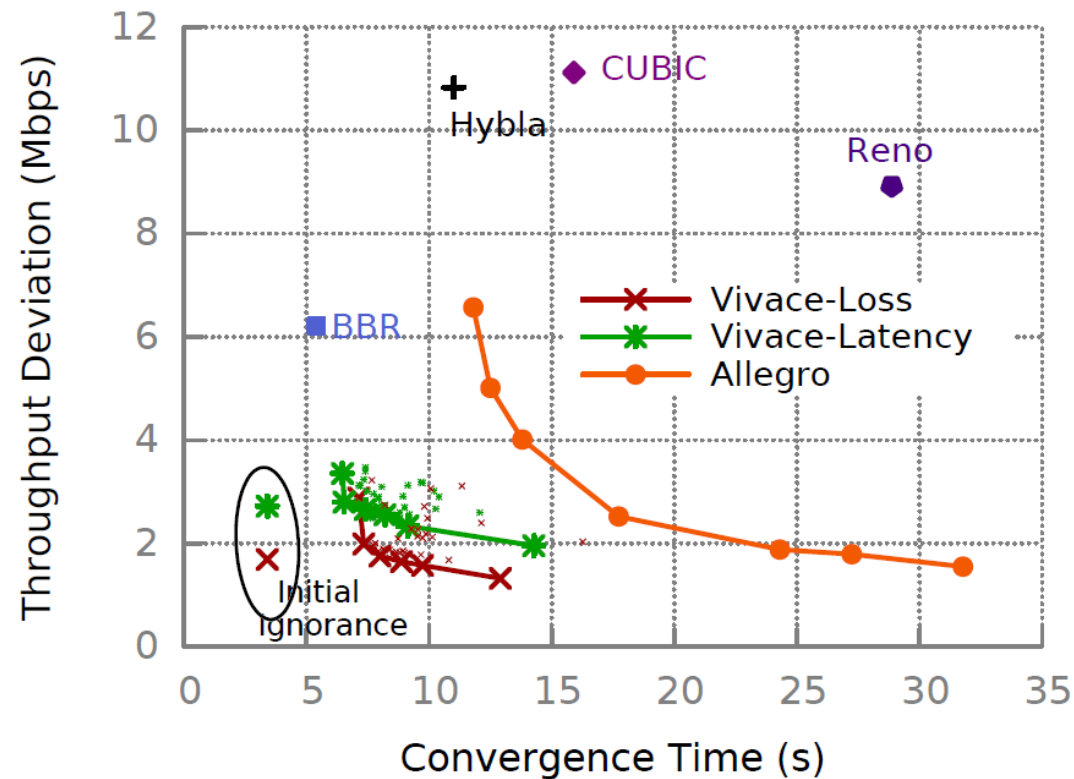
- Latency awareness (100Mbps, 30ms RTT Emulab bottleneck link)



< 0.5% loss with 13.5KB buffer
55% smaller than TCP CUBIC

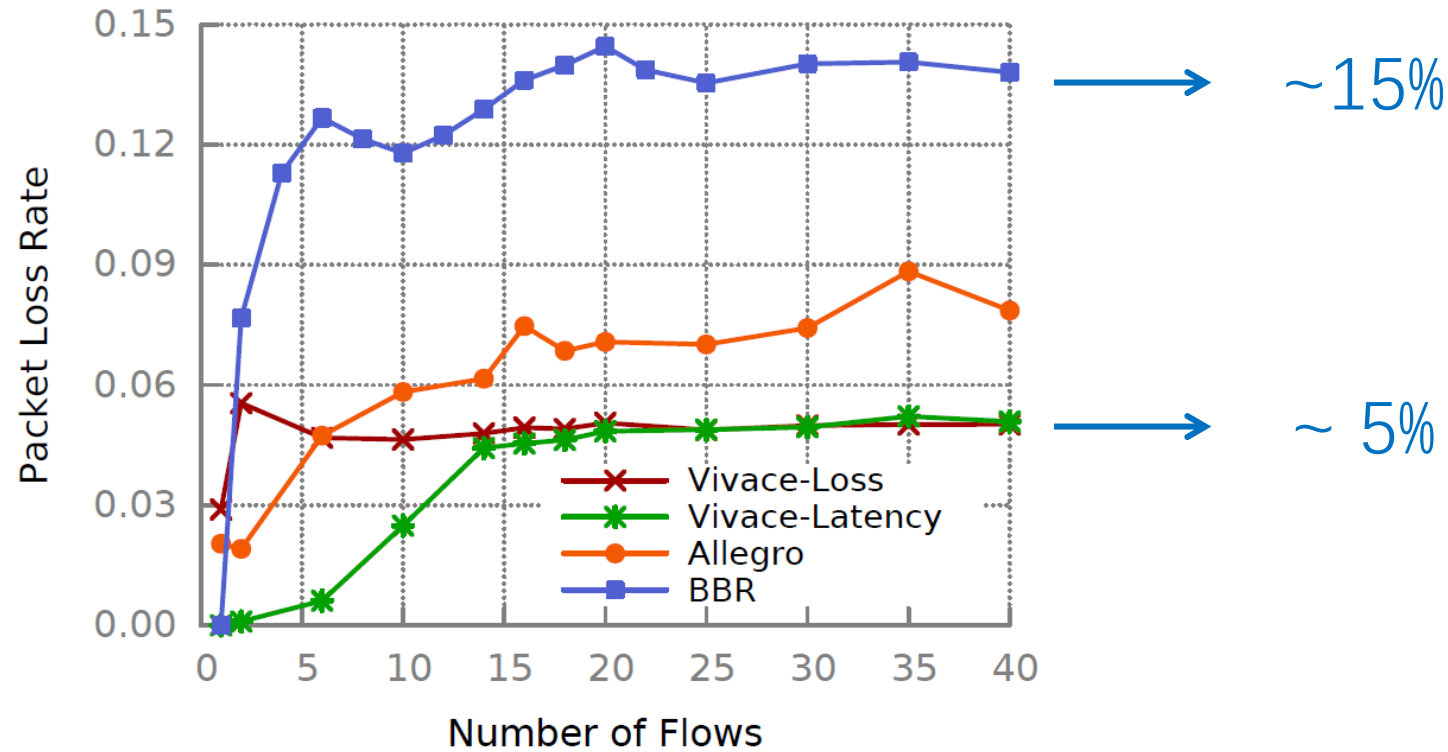
Vivace Rate Control Performance

- Convergence Speed/Stability Tradeoff (100Mbps, 30ms RTT, 75KB buffer)

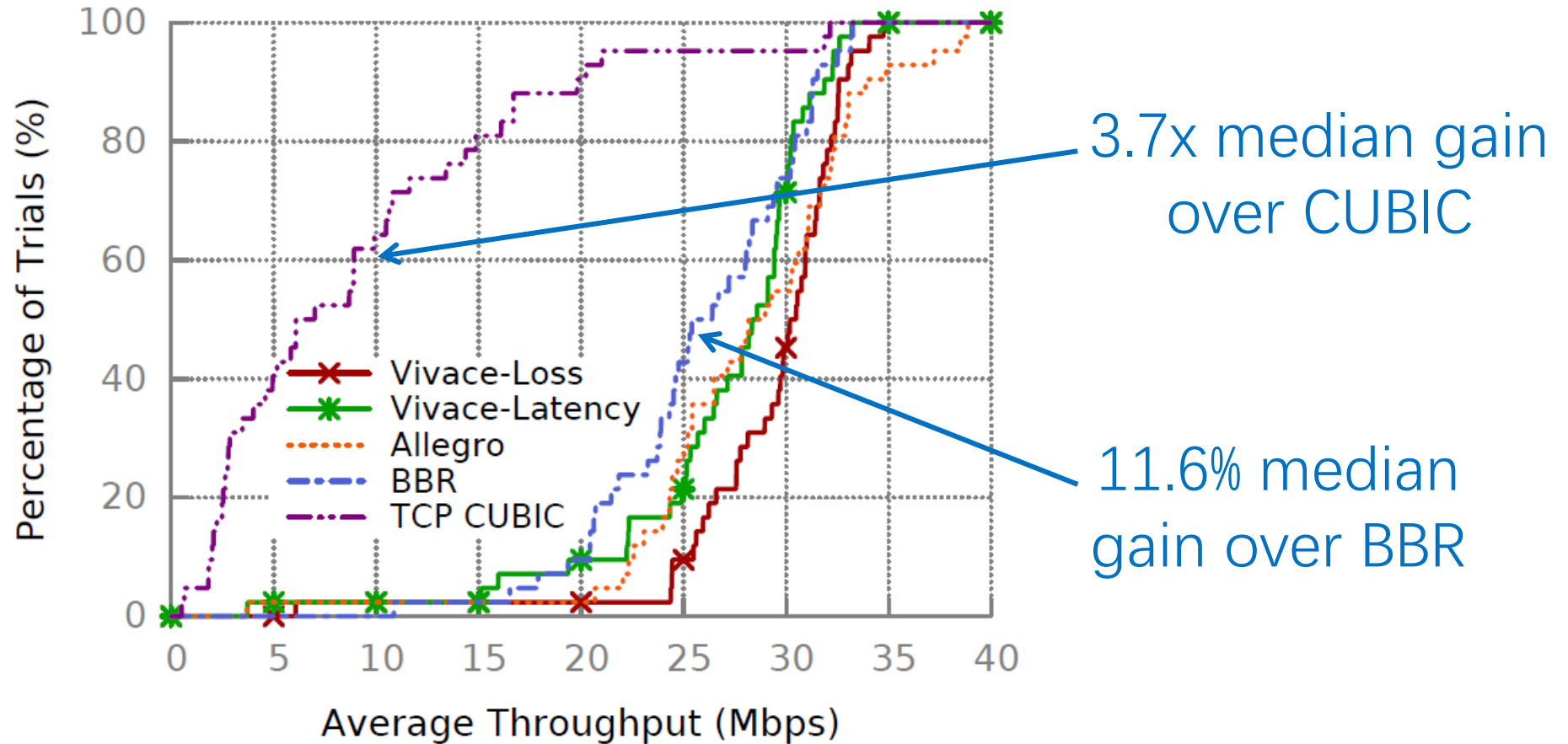


Insights from No-Regret Guarantee

- Random loss tolerance vs. Congestion loss (8Mbps, 25KB per-flow share)



Performance in Real-World



Limitation of No-Regret

“Sender's choices of rates are asymptotically (across time) no worse, utility-wise, than sending at what would have been (in hindsight) the *best fixed rate*”



Still make sense in highly dynamic environment?